# EXACT. SOLUTIONS OF THE AXIALLY SYMMETRIC EULER EQUATIONS $\dagger$ 

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New classes of exact solutions of Euler's equations are found, which describe steady axially symmetric flow with a vortex. Examples of solutions corresponding to fluid flows with a free boundary are given. Copyright © 1996 Elsevier Science Ltd.

1. We consider the following equation for the stream function $\psi(z, r)$ describing steady axially symmetric (with vortex) flows of an ideal incompressible fluid [1], which is also known as the Grad-Shafranov equation in plasma physics

$$
\begin{equation*}
\Psi_{z z}+\Psi_{r r}-r^{-1} \Psi_{r}=r^{2} F-H \tag{1.1}
\end{equation*}
$$

where $F$ and $H$ are arbitrary functions of $\psi$. We will seek solutions $\psi$ of (1.1) such that for any smooth function $\phi$ the composition $\chi=\phi \cdot \psi$ is also a solution of some equation

$$
\begin{equation*}
\chi_{z z}+\chi_{r r}-r^{-1} \chi_{r}=r^{2} F_{1}(\chi)-H_{1}(\chi) \tag{1.2}
\end{equation*}
$$

Solutions having this property will be called functionally-invariant. Functionally-invariant solutions of the wave equation were constructed in [2] and their group-theoretic interpretation was given in [3].

Henceforth we shall assume that $\psi_{z} \neq 0$ and $\psi_{r} \neq 0$. Substituting $\phi \cdot \psi$ in place of $\chi$ in (1.2), we obtain

$$
\begin{equation*}
\phi^{\prime}(\psi)\left(\psi_{z z}+\psi_{r r}-r^{-1} \psi_{r}\right)+\phi^{\prime \prime}(\psi)\left(\psi_{z}^{2}+\psi_{r}^{2}\right)=r^{2} F_{1}(\phi(\psi))-H_{1}(\phi(\psi)) \tag{1.3}
\end{equation*}
$$

If $\phi^{\prime \prime} \neq 0$, then from (1.1) and (1.3) we obtain the equation

$$
\begin{align*}
& \Psi_{z}^{2}+\psi_{r}^{2}=r^{2} C_{2}+C_{1}  \tag{1.4}\\
& C_{1}(\psi)=-\left(H_{1}(\phi(\psi))-\phi^{\prime}(\psi) H(\psi)\right) / \phi^{\prime \prime}(\psi) \\
& C_{2}(\psi)=\left(F_{1}(\phi(\psi))-\phi^{\prime}(\psi) F(\psi)\right) / \phi^{\prime \prime}(\psi)
\end{align*}
$$

Multiplying (1.1) by $\psi_{z}$ and subtracting from it Eq. (1.4) differentiated with respect to $z$ and multiplied by two, we arrive at the equation

$$
\begin{align*}
& r \psi_{z}\left(\psi_{r} / r\right)_{r}-r \psi_{r}\left(\psi_{r} / r\right)_{z}=\left(A_{2}(\psi) r^{2}+A_{3}(\psi)\right) \psi_{z}  \tag{1.5}\\
& A_{2}(\psi)=F-C_{2}^{\prime} / 2, \quad A_{3}(\psi)=-\left(H+C_{1}^{\prime} / 2\right)
\end{align*}
$$

Integrating the latter, we get

$$
\begin{equation*}
\psi_{r}=A_{1}(\psi) r+A_{2}(\psi) r^{3} / 2+A_{3}(\psi) r \ln r \tag{1.6}
\end{equation*}
$$

The compatibility of (1.4) and (1.6) can be investigated by standard methods. Expressing $\psi_{z}$ in (1.4) in terms of $\psi$ and $r$ using (1.6), after cross-differentiation we obtain

$$
\begin{aligned}
& K_{1} r \ln ^{2} r+K_{2} r^{3} \ln r+K_{3} r \ln r+K_{4} r^{5}+K_{5} r^{3}+K_{6} r=0 \\
& K_{1}=-2 A_{3}^{2}, \quad K_{2}=-8 A_{3} A_{2}+C_{2}^{\prime} A_{3}-2 C_{2} A_{3}^{\prime}
\end{aligned}
$$

$$
\begin{align*}
& K_{3}=-4 A_{1} A_{3}+C_{1}^{\prime} A_{3}-2 C_{1} A_{3}^{\prime}, \quad K_{4}=-6 A_{2}^{2}+C_{2}^{\prime} A_{2}-2 C_{2} A_{2}^{\prime}  \tag{1.7}\\
& K_{5}=-8 A_{1} A_{2}-2 A_{2} A_{3}+C_{1}^{\prime} A_{2}+C_{2}^{\prime} A_{1}-2 C_{1} A_{2}^{\prime}-2 C_{2} A_{1}^{\prime} \\
& K_{6}=2 C_{2}-2 A_{1} A_{3}-2 A_{1}^{2}+C_{1}^{\prime} A_{1}-2 C_{1} A_{2}^{\prime}
\end{align*}
$$

Since $\psi_{z} \neq 0$, Eq. (1.7) implies the six equations $K_{i}=0$. By the first equation, $H+C^{\prime} / 2=0$. Then the second and third equations become identities, and the fourth to sixth equations take the form

$$
\begin{align*}
& -6 A_{2}^{2}+C_{2}^{\prime} A_{2}-2 C_{2} A_{2}^{\prime}=0  \tag{1.8}\\
& -8 A_{1} A_{2}+C_{1}^{\prime} A_{2}+C_{2}^{\prime} A_{1}-2 C_{1} A_{2}^{\prime}-2 C_{2} A_{1}^{\prime}=0 \\
& 2 C_{2}-2 A_{1}^{2}+C_{1}^{\prime} A_{1}-2 C_{1} A_{2}^{\prime}=0
\end{align*}
$$

Using the above, we can write (1.6) as follows:

$$
\begin{equation*}
\psi_{r}=A_{1}(\psi) r+A_{2}(\psi) r^{3} \tag{1.9}
\end{equation*}
$$

and the functions $F$ and $H$ can be expressed by

$$
\begin{equation*}
F=C_{2}^{\prime} / 2+2 A_{2}, \quad H=-C_{1}^{\prime} / 2 \tag{1.10}
\end{equation*}
$$

It is obvious that every solution of Eqs (1.4) and (1.9) is functionally-invariant. It can be shown that Eq. (1.1), taking (1.10) into account, is satisfied identically by (1.4) and (1.9). Therefore we have proved the following result.

Theorem. The function $\psi(z, r)$ is a functionally-invariant solution of Eq. (1.1) if and only if it satisfies Eqs (1.4) and (1.9), where $A_{i}, C_{i}(i=1,2)$ are solutions of (1.8).
2. Among the functionally-invariant solutions one can distinguish those corresponding to fluid flow with free boundary. If the pressure is assumed to depend only on the stream functions $p=p(\psi)$ it can be shown that for any constant $\psi_{0}$ the conditions for the existence of free boundary [4] will be satisfied for the surface $\psi=\psi_{0}$. Using Bernoulli's equation

$$
p+|\mathbf{u}|^{2} / 2=R(\psi)
$$

for an incompressible fluid in the axially symmetric case, we arrive at the conclusion that the square of the velocity depends on the stream function $|u|^{2}=T(\psi)$, which is in turn equivalent to Eq. (1.4) for $C_{1} \leqslant 0$. It follows that for any functionally-invariant solution $\psi$ of Eq. (1.1) the surface $\psi(z, r)=\psi_{0}=$ const can serve as a free boundary subject to the condition $C_{1}\left(\Psi_{0}\right) \leqslant 0$.
3. The problem arises of finding the solutions of system (1.8). First we will consider the case $A_{2}=$ 0 . Then, the first equation in (1.8) is an identity. Without loss of generality we can set $A_{1}=1$. The solutions of Eq. (1.1) corresponding to other values of $A_{1}$ can be obtained as a result of the superposition of a function $\phi$ and the solution obtained for $A_{1}=1$. The second and third equations (1.8) can be simplified considerably.

$$
C_{2}^{\prime}=0, \quad 2 C_{2}-2+C_{1}^{\prime}=0
$$

Their solution is $C_{2}=k, C_{1}=l+(2-2 k) \psi$, where $k, l, \in R$. Substituting the values just found into the right-hand sides of (1.4) and (1.9) and solving the resulting overdetermined system, we obtain

$$
\psi= \begin{cases}r^{2} / 2+\sqrt{l} z+\gamma, & k=1, l \geqslant 0  \tag{3.1}\\ r^{2} / 2+(1-k)(z+\gamma) / 2+l /(2-2 k), & k \neq 1\end{cases}
$$

where $\gamma$ is an arbitrary constant. In the case when $k>1$ and $\psi_{0} \geqslant l /(2 k-2)$ the surface $\psi=\psi_{0}$ (which is a one-sheeted hyperboloid if the second inequality is strict, and a circular cone otherwise) can be regarded as a free boundary. As has been mentioned above, $\phi \cdot \psi$, where $\psi$ is given by (3.1), is a solution of Eq. (1.1). Moreover

$$
F=-k \tau^{\prime \prime} / \tau^{\prime 3}, \quad H=l \tau^{\prime \prime} / \tau^{\prime 3}+(1-k) \tau^{\prime \prime} \tau / \tau^{\prime 3}+(k-1) / \tau^{\prime}
$$

Here $\phi$ is an arbitrary function and $\tau$ is its inverse.
We will now consider the case when $A_{2} \neq 0$. We make the substitution

$$
A_{1}=B A_{2}, \quad C_{1}=(K+B) E A_{2}^{2}, \quad C_{2}=E A_{2}^{2}
$$

where $K(\psi), E(\psi), B(\psi)$ are new unknown functions. Then system (1.8) will be equivalent to the following

$$
\begin{equation*}
A_{2} E^{\prime}=6, \quad A_{2} E K^{\prime}=E / K-4 B-6 K, \quad A_{2} K B^{\prime}=1 \tag{3.2}
\end{equation*}
$$

Without loss of generality, we can set $A_{2}=\psi^{3}$ in (3.2). Then the resulting system admits of the expansion operator $X=2 E \partial_{E}+K \partial_{K}+B \partial_{B}-\psi \partial_{\psi}$, the solution invariant under this operator being given by

$$
E=-3 \psi^{-2}, \quad B= \pm 3 \psi^{-1}, \quad K=\mp \psi^{-1} / 3
$$

It can be verified that there are no real solutions when $B=3 \psi^{-1}$ and $K=-\psi^{-1} / 3$, so that in this case (1.4) implies that $\psi_{z}^{2}+\psi_{r}^{2}<0$. When $B=-3 \psi^{-1}, K=-\psi^{-1} / 3$, from (1.4) and (1.9) we obtain the following system from which to find $\psi$

$$
\psi_{z}^{2}+\psi_{r}^{2}=-3 \psi^{4} r^{2}+8 \psi^{3}, \quad \psi_{r}=\psi^{3} r^{3}-3 \psi^{2} r
$$

This system admits of the operator $Y=z \partial_{z}+r \partial_{r}-2 \psi \partial_{\psi}$. The solutions invariant under $Y$ are given by

$$
\begin{equation*}
\psi=\frac{1}{r^{2}}\left(1 \pm \frac{z}{\sqrt{r^{2}+z^{2}}}\right) \tag{3.3}
\end{equation*}
$$

The choice of sign obviously does not matter. Other solutions of the system are either trivial (i.e. independent of $z$ ) or can be obtained from (3.3) by a translation along the $z$ axis.

The function $\phi \cdot \psi$ is a solution of Eq. (1.1) when

$$
F=-4 \tau^{3} / \tau^{\prime}+3 \tau^{4} \tau^{\prime \prime} / \tau^{\prime 3}, \quad H=12 \tau^{2} / \tau^{\prime}-8 \tau^{3} \tau^{\prime \prime} / \tau^{\prime 3}
$$

Here, as before, $\tau(\psi)$ is the inverse function to $\phi$.
It should be noted that solutions of the form $\phi \cdot \psi$ for $\phi=2 \ln \psi+\delta$ and $\phi=\varepsilon \psi^{2(n-1)}$, where $\varepsilon, \delta \in$ $R$, are invariant solutions with respect to the admissible operators $z \partial_{z}+r \partial_{r}-4 \partial_{\psi}$ and, respectively, $z \partial_{z}$ $+r \partial_{r}-4(n-1)^{-1} \psi \partial_{\psi}$, which were found for the first time in [5].
4. Apart from those described above, we have not succeeded in finding other explicit representations of functionally-invariant solutions of Eq. (1.1). Nevertheless, the level curves of $\psi$ corresponding to functionally-invariant solutions can be constructed numerically. In this way a picture of the behaviour of trajectories of the corresponding solutions can be built up. One does not have to solve (1.8) to construct a separate level curve; it suffices to use the equation

$$
d z / d r=-\psi_{r} / \psi_{z}
$$

When constructing the level curves the initial points were varied along the line $z=z_{0}=$ const. Along with solving Eq. (1.9), it turned out to be necessary to solve system (1.8) simultaneously.

Below we present some computational results. To fix our ideas we will put $E=\psi$ everywhere. Then the first equation in (3.2) implies that $A_{2}=6$. In addition, the initial point for constructing the level curve was chosen to be on the $O z$ axis. When constructing the level curves shown in Fig. 1, we selected the initial data to be $r=2, B=-1.98, E=8.17, K=-1.99 \times 10^{-2}$. The values $\psi=8.17 ; 11.1 ; 17.0 ; 29.1$ of the stream function correspond to curves 1-4. For each of the level curves shown $\psi=\psi_{0} C_{1}\left(\psi_{0}\right) \leqslant$ 0 . It follows that with each of them one can associate a surface which is a free boundary. The streamlines are obviously open. We used the following initial data for the level curves in Fig. 2: $r=2.829, B=$ $-5.84, E=5.98, K=4.10$. For curves $1-5 \psi=5.98 ; 34.6 ; 44.2 ; 53.7 ; 82.5$, respectively. For each level curve $\psi=\psi_{0}$ that does not intersect the axis of rotation the condition $C_{1}\left(\psi_{0}\right) \leqslant 0$ is also satisfied. The resulting solution can be interpreted as the motion of a fluid with toroidal free boundary.


Fig. 1.


Fig. 2.
5. Let us consider a more general form of Eqs (1.4) and (1.9)

$$
\begin{equation*}
\psi_{r}=A(\psi, r), \quad \psi_{z}^{2}+\psi_{r}^{2}=C(\psi, r) \tag{5.1}
\end{equation*}
$$

The compatibility condition for these equations is given by

$$
\begin{equation*}
C_{r}-2 A A_{r}+C_{\psi} A-2 C A_{\psi}=0 \tag{5.2}
\end{equation*}
$$

Equation (1.1) will be satisfied by virtue of (5.1) if and only if

$$
\begin{equation*}
C_{\psi} / 2+A_{r}-A / r=F r^{2}-H \tag{5.3}
\end{equation*}
$$

Equations (5.1)-(5.3) can be regarded as a group stratification [6] of Eq. (1.1) relative to the oneparameter group generated by the operator $\vartheta_{z}$, Eqs (5.1) forming an automorphic system and Eqs (5.2) and (5.3) forming a resolving system.

We shall seek a solution of system (5.2), (5.3) in the form

$$
A=\sum_{i=1}^{m} A_{i}(\psi) S_{i}(r), \quad C=\sum_{j=1}^{n} C_{j}(\psi) T_{j}(r)
$$

where $m$ and $n$ are certain natural numbers. The case $m=n=2$ corresponds to functionally-invariant solutions. It can be shown that the case $m=1, n=3$ corresponds to solutions of the form $\psi=f(z) g(r)$
when $F=A \psi$ and $H=B \psi \ln \psi[5]$. It turns out that for $m=1$ and $n=3$ other solutions of Eqs (5.2), (5.3) of the given form exist.

For example, let $S_{1}=r^{-1}, T_{1}=r^{-1}, T_{2}=1, T_{3}=r^{2}$. Substituting the above representations for $A$ and $C$ into Eqs (5.2) and (5.3), we obtain the equations

$$
\begin{aligned}
& \left(-2 C_{1}+2 A_{1}^{2}+C_{1}^{\prime} A_{1}-2 C_{1} A_{1}^{\prime}\right) r^{-3}+\left(C_{2}^{\prime} A_{1}-2 C_{2} A_{1}^{\prime}\right) r^{-1}+\left(2 C_{3}+C_{3}^{\prime} A_{1}-2 C_{3} A_{1}^{\prime}\right) r=0 \\
& \left(C_{1}^{\prime} / 2-2 A_{1}\right) r^{-2}+C_{2}^{\prime} / 2+C_{3}^{\prime} / 2 r^{2}=F r^{2}-H
\end{aligned}
$$

Equating the coefficients of like powers of $r$ and solving the resulting system of ordinary differential equations, we find that

$$
\begin{array}{ll}
C_{1}=\left(k \psi^{2}-1\right)^{2} / k, & C_{2}=\beta \psi^{2}\left(k \psi^{2}-1\right)^{2} \\
C_{3}=\alpha \psi^{4}\left(k \psi^{2}-1\right), & A_{1}=\psi\left(k \psi^{2}-1\right) \\
F=\alpha \psi^{3}\left(3 k \psi^{2}-2\right), & H=\beta\left(k \psi^{2}-1\right)\left(\psi-3 k \psi^{3}\right) ;
\end{array} \quad \alpha, \beta, k \in R=\$
$$

The function $\psi$ is specified, apart from an arbitrary additive constant. Besides, no solution corresponding to a linear equation of the form (1.1) is given. The solution of Eq. (1.1) for the above $A$ and $C$ is given by

$$
\psi=\left(k\left(1+M r^{2}\right)\right)^{-1 / 2}
$$

where $M$ is the Weierstrass function, satisfying the equation

$$
M_{z}^{2}=4 M^{3}+4 \beta M^{2}-4 \alpha M / k
$$

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